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## **ELECTRONICS ENGINEERING**

# ACE ACADEMY

**Topper Handwritten Notes**Computer Engineering

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#### 1. OPERATING SYSTEM

- \* <u>os:</u>-

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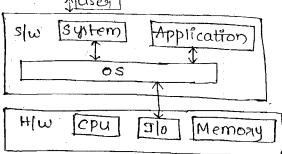
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OS is the software which provides Interface by compu

hardware & user.



\* Goal of a good os:-

- 1. Convienience (user friendly) Ex! Windows
- 2. Efficient (performance)
- 3. Portability: os should run on diff. hardware sets.
- 4. Scalability: can add new things
- 5. Robustness: If any prolim occursinos, Pc should not crash.
  - \* Type of os:
    - 1) uni-programming os:-
- O os allows only one process in the main memory
- If the process goes for I/o execution, DS RAM

  then cpu will be ideal. Hence cpu, utilization p1

  is less.
  - 2) <u>multi-programming os:</u>
- This can allow multiple processes in main memory
- other process is a vailable to run on cpu. Hence better cpu utilization.
  - No. of processes in the main memory is known RAM as degree of multi-programming.

OS PI

P2...

<u>P3</u> -24

- →If degree of multi-programming is Increased, then cpu utilization increases (but up to a certain limit).
- \* Types of multi-programming os:-
  - 1) Non-preemptive
  - 2) pre-emptive.
  - 1) Non-pre-emptive:-

Once a process goes for execution, then it leaves opu by its own wish (either process complete for) gray for Io)

2) pre-emptive:

If a process goes for execution, it can be taken out from cpu forcefully [Interrupti]

\* Multi-tasking os: - (Time sharing os):-

It is an extension of multi-prog. os in which processes execute in round-robin fashion and switching by processes is very fast, so that ever understands that all the processes are sunning in parallel

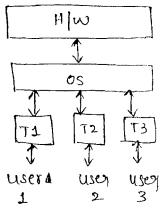
PL P2 P3 P1 P2 P3

\* cpu time is shared threqually bln all available processors.

\* Multi-user os:-

This os can allow multiple users to use the comptator system simultaneously.

\* T1, T2, T3 are terminals [keyboard, mouse, display unit].



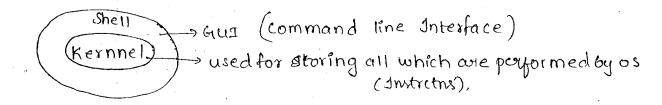
\* multi - processing os:-This os needed on a machine, which has multiple cpu 1) Tightly bound shared memory. 0 loosely bound distributed as.  $\Theta$ Tightly bound :-0 CPU1 CPU2 1 CPU3 - only one main memory.  $\mathbf{O}$ No of cpu's Main memory 0 2) loosely bound :kpu-1 0 CPU2 CPU3 No of cpu's & main memories. 7 Distributed o'smmi mm2 mmi • 0 \* Real-time Os: 0 Ex: ATM. If we didn't enter PIN," 0 -This os runs on a machine which has real time dat O $\mathbf{O}$ to process. - In this os, every process has deadlines. > The process should execute with in deadline time. O real time os [ If pres not done in dead! 1) Hard it stops Imdtly].  $\mathbf{O}$ real time os Soft [opp.to band]. - not Imdtly. O OEmbedded os:-0 Embedded system is an expert system attached with () mechanical machines to make those machines Intelligent. 0 This sys. Includes hardware [process, memory] and the progs 0 for the Interaction by mechanical machine & processor. 0 - This set of prog's is known as embedded os.

- Interaction of user with embedded os is 'Veryless."

\* Hand - held os: -

Os running on hand-held devices like mobiles, tablets
ete,

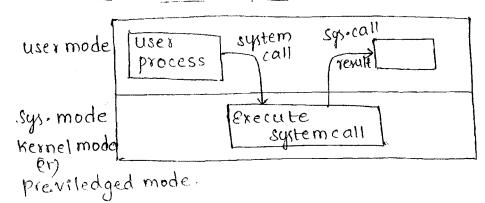
\* Parts of os:-



## \* Services of os: -

- 1) user Interface
- 2) Prog. execution.
- 3) I/o operations
- 4) Resource management
- 5) file system manipulation
- 6) Interprocess connetn.
- 7) Error detection.

## \* Dual mode of oprtn:-



\*\* Dynamic libraries are not need in os

\* process which has just terminated but hasto yet relinquish its resource called as "tombie process."

8) protection & Security